

A3000-150

| Operational time between charge | 150 days (ADS in low power mode) |
|------------------------------------|---------------------------------------|
| · · | , , , |
| Maximum deployment depth | 3600 meters |
| Operating temperature range | -10 to +55 °C |
| Data acquisition * | |
| Number of channels | 4 |
| ADC resolution | 24 / 32 bit |
| Sample interval | 0.25, 0.5, 1 and 2 ms |
| Pre-amplifier gain, adjustable | 0 to 36 dB in steps of 6 dB |
| Gain Relative uncertainty | 0.5 % |
| Recording bandwidth (-3dB) | DC – 0.413 x f _{DATA} |
| Anti-aliasing filter | 206.5 Hz (82.6 % of Nyquist) @ 2ms 2) |
| | Sinc+FIR, Linear phase |
| High pass filter | Programmable 0.1 – 10 Hz, or disabled |
| High pass filter roll off | 6 dB/octave |
| Maximum input signal | ± 2500 mV @ 0 dB |
| | ± 625 mV @ 12 dB |
| | ± 156 mV @ 24 dB |
| | ± 39 mV @ 36 dB |
| Equivalent Input Noise *** | 0.95 µVrms @ 0 dB |
| | 0.31 µVrms @ 12 db |
| | 0.21 µVrms @ 24 dB |
| | 0.20 μVrms @ 36 dB |
| Dynamic Range @ 0dB gain | 130 dB Geophone, 125 dB Hydrophone |
| Total harmonic distortion (THD) | < -100 dB Geophone @ 0 dB gain |
| | <-119 dB Hydrophone @ 0 dB gain |
| Crossfeed | >120 dB |
| Common mode rejection ratio (CMRR) | > 90 dB (Geophone) |
| | > 90 dB (Hydrophone) |

Self-test, diagnostic, and calibration

Transponder (Optional)

| Type (Integrated design) | USBL 26kHz | |
|--------------------------|-----------------|--|
| Geophone | | |
| Туре | Omnidirectional | |
| Number of Geophones | 3 | |
| Configuration | Orthogonal | |
| Resonance frequency | 14 Hz | |
| Sensitivity | 80.0 V/m/s | |
| Damping | 0.7 | |
| | | |

| Hydrophone | | |
|--|---|--|
| Frequency response (-3dB) | 1,05 Hz – 30 kHz | |
| Sensitivity | - 201 dB re: 1V/µPa (8.9V/bar) | |
| Equivalent Input self-noise (1-1000Hz) | 78 dB re: 1µPa, (0.08µBar) | |
| Spectral: | 54 dB re: 1µPa/√Hz @ 10 Hz | |
| | 42 dB re: 1µPa/√Hz @ 100 Hz | |
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| Tilt Sensor | | |
| Туре | 3-axis MEMS inclinometer | |
| Range X and Y (Roll and Pitch) | ± 90 ° | |
| Relative uncertainty | ±1° | |
| Magnetometer (azimuth angle) | | |
| Range | 0 - 360 ° | |
| Relative uncertainty | ± 5 ° (< ±55 ° from Equator) | |
| Internal Powersupply and Charg | er | |
| Charger operating voltage range | 36–72 VDC | |
| Charger insulation voltage, input/output | 1500 VDC | |
| Recharge time to 80% SOC | 16 h | |
| Charging temperature range | +4°C - +40°C | |
| Battery and Battery Managemen | t System | |
| Chemistry | Li-lon | |
| BMS | Fuel gauging, diagnostic and protection | |
| Certification | UN38.3 | |
| Precision clock | | |
| Clock type | Ultra-precise OCXO clock | |
| Time drift correction | inApril's proprietary solution | |
| Typical error (corrected, post-acquisition) | < ± 1.0 ms after 130 days | |
| Data capture memory | | |
| Туре | Embedded managed NAND flash | |
| Storage capacity total | 128 GByte | |
| Communication link; data captu | re and diagnostic | |
| Ethernet over copper | 100 base-TX | |
| Mechanical specification | | |
| Position of normal use | ±180° | |
| Weight (air / water) | 21.2 kg (9,7 kg in seawater) | |
| Dimensions | 319mm(L) x 287mm(w) x 115/145mm(h) | |
| Notes | | |
| - @ 2ms sampling interval, 25°C, 31.25 H | z, internal test, unless otherwise noted) | |
| - Recording bandwidth = $0.413 \times f_{DATA}$ | | |
| f _{DATA} = sampling frequency =1/Sample Interval (Hz) | | |
| - for geophone channel, and hydrophone channel above 10 Hz | | |
| - 1.2 μVrms @ 0 dB for frequency above low cut | | |
| - for geophone channel, and hydrophone of | channel above 10 Hz | |

10.23